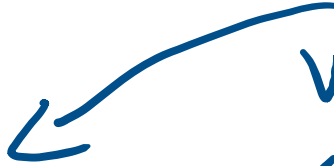


Coresets

Coreset

(informally): a small
subset of the input
that "preserves" useful
properties of the input

ideally
very small
compared to
 n



Example

· Minimum Enclosing Ball problem

Given: $P = \{p_1 \dots p_n\} \subseteq \mathbb{R}^d$

Find: $x \in \mathbb{R}^d$ minimizing

$$\max_{p \in P} \{d(p, x)\}$$

Coreset: $Q \subseteq P$ such that for all $y \in \mathbb{R}^d$,

$$\max_{q \in Q} \{d(q, y)\} \approx \max_{p \in P} \{d(p, y)\}.$$

Coreset

(formally): given a cost function

S is an ϵ -coreset for P if

- $(1-\epsilon) \text{cost}(P) \leq \text{cost}(S) \leq \text{cost}(P)$
- $(1-\epsilon) \text{cost}(P) \leq \text{cost}(S) \leq (1+\epsilon) \text{cost}(P)$
- $\text{cost}(S) \leq \text{cost}(P) \leq (1+\epsilon) \text{cost}(S)$

} depends
on the
problem...

Example

- Minimum Enclosing Ball problem

Given: $P = \{p_1 \dots p_n\} \subseteq \mathbb{R}^d$

Find: $x \in \mathbb{R}^d$ minimizing

$$\text{cost}(P, x) = \max_{p \in P} \{d(p, x)\}$$

Coreset: $Q \subseteq P$ such that for all $y \in \mathbb{R}^d$, $(1-\varepsilon)\text{cost}(P, y) \leq \text{cost}(Q, y) \leq \text{cost}(P, y)$

ϵ -coreset for MEB

Alg:

$S_1 \leftarrow \{ \text{an arbitrary } p \in P \}$

for $i = 1$ to T  $\leftarrow$ determine later

$c_i \leftarrow$ MEB center of S_i

$p_i \leftarrow \arg \max_{p \in P} d(c_i, p)$

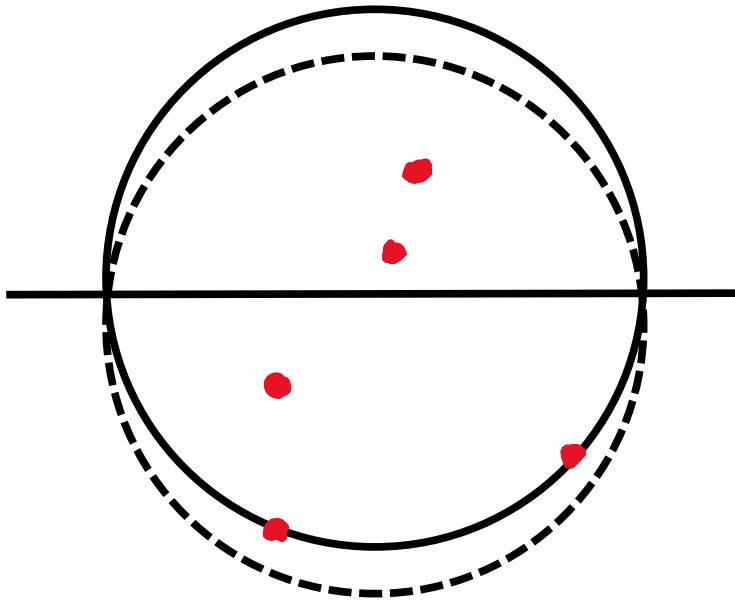
$S_{i+1} \leftarrow S_i \cup \{p_i\}$

return S_{T+1}

ϵ -coreset for MEB

Analysis:

Lemma: Let B be the MEB for P with center C & radius R . Any halfspace containing C contains $p \in P$ with $d(p, C) = R$.



Pf: Suppose not. Then can shift the ball perpendicular to halfplane $\Rightarrow$ no points on boundary.

We can then shrink ball $\Rightarrow$ not minimum.

ϵ -coreset for MEB

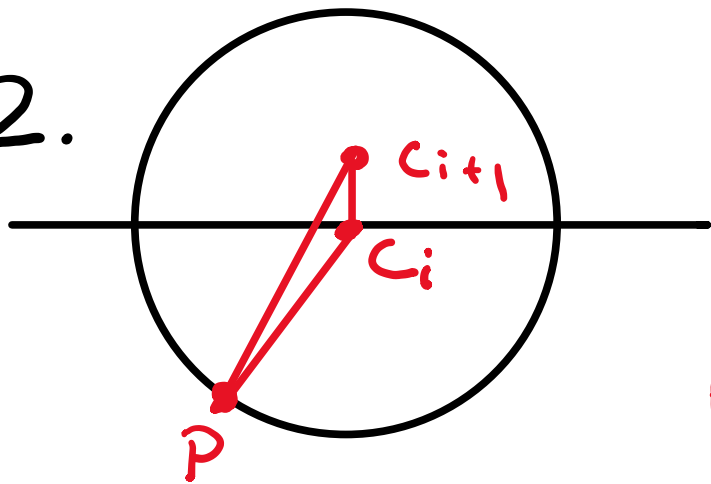
Analysis: R = radius of MEB(P) $\lambda_i = \frac{r_i}{R}$
 r_i = radius of MEB(S_i)

Goal: identify T such that $\lambda_T \geq 1 - \epsilon$

1. $\exists q \in P$ s.t. $d(q, c_i) \geq R$

$$r_{i+1} \geq d(q, c_{i+1}) \geq d(q, c_i) - d(c_i, c_{i+1}) \\ \geq R - d(c_i, c_{i+1})$$

2.



Suppose $d(c_i, c_{i+1}) > 0$ (else done)

By Lemma $\exists p, d(p, c_i) = r_i$

$$r_{i+1} \geq d(c_{i+1}, p) \geq \sqrt{r_i^2 + d(c_i, c_{i+1})^2}$$

ϵ -coreset for MEB

Analysis: R = radius of MEB(P) $\lambda_i = \frac{r_i}{R}$
 r_i = radius of MEB(S_i)

Goal: identify T such that $\lambda_T \geq 1 - \epsilon$

$$\Rightarrow \lambda_{i+1} \geq \frac{1}{R} \max \left\{ R - d(c_i, c_{i+1}), \sqrt{\lambda_i^2 R^2 + d(c_i, c_{i+1})^2} \right\}$$

minimized when $R - d(c_i, c_{i+1}) = \sqrt{\lambda_i^2 R^2 + d(c_i, c_{i+1})^2}$

$$\Rightarrow d(c_i, c_{i+1}) = \frac{(1 - \lambda_i^2) R}{2}$$

$$\lambda_{i+1} \geq \frac{R - d(c_i, c_{i+1})}{R} = \frac{1 + \lambda_i^2}{2} \Rightarrow \lambda_i \geq 1 - \frac{1}{1 + i/2}$$

ϵ -coreset for MEB

Analysis: R = radius of MEB(P) $\lambda_i = \frac{r_i}{R}$
 r_i = radius of MEB(S_i)

Goal: identify T such that $\lambda_T \geq 1 - \epsilon$

$$\Rightarrow \lambda_T \geq 1 - \frac{1}{1 + T/2} \geq 1 - \epsilon$$

suffices to set $T \geq \frac{2}{\epsilon}$.

ϵ -coreset for MEB

Alg:

$S_1 \leftarrow \{ \text{an arbitrary } p \in P \}$

for $i = 1$ to $T = 2/\epsilon$

$c_i \leftarrow \text{MEB center of } S_i$

$p_i \leftarrow \arg \max_{p \in P} d(c_i, p)$

$S_{i+1} \leftarrow S_i \cup \{p_i\}$

return S_{T+1}

Size of
 ϵ -coreset is
independent of n

Stre

Us

-

So

- (Strong merge. It p

Streaming Coresets

Reduce + Strong Merge Properties

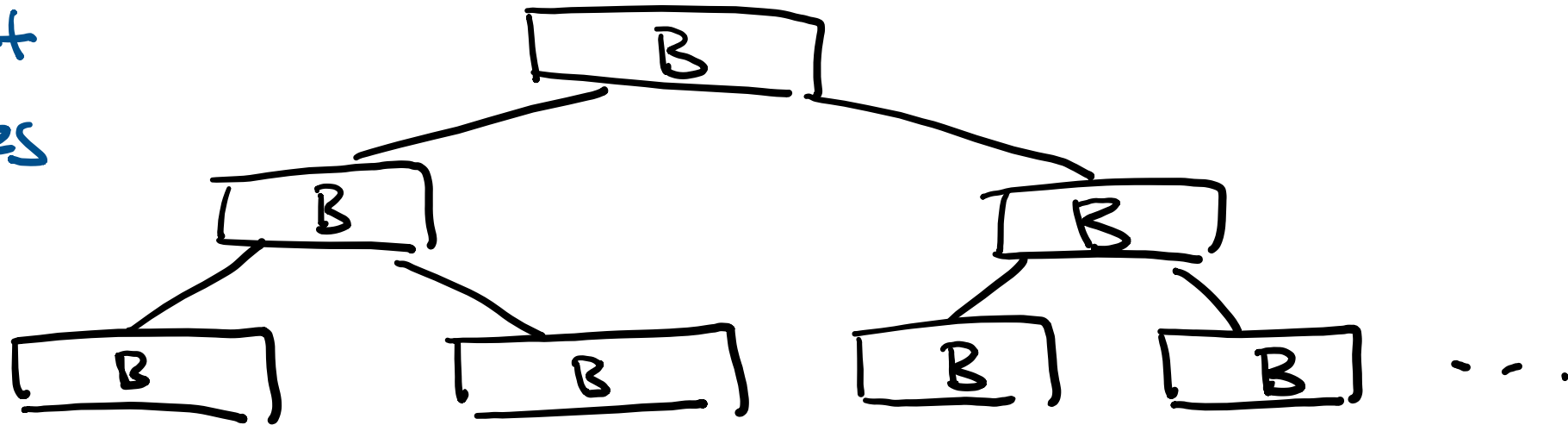
$\Rightarrow$ use Merge & Reduce Paradigm

Suppose $f(\epsilon)$ space for ϵ -coreset.

$$\text{Set } B = f(\epsilon / \log n)$$

at each level:

$\epsilon / \log n$ -coreset
of child nodes



Streaming Coresets

Reduce + Strong Merge Properties

$\Rightarrow$ use Merge & Reduce Paradigm

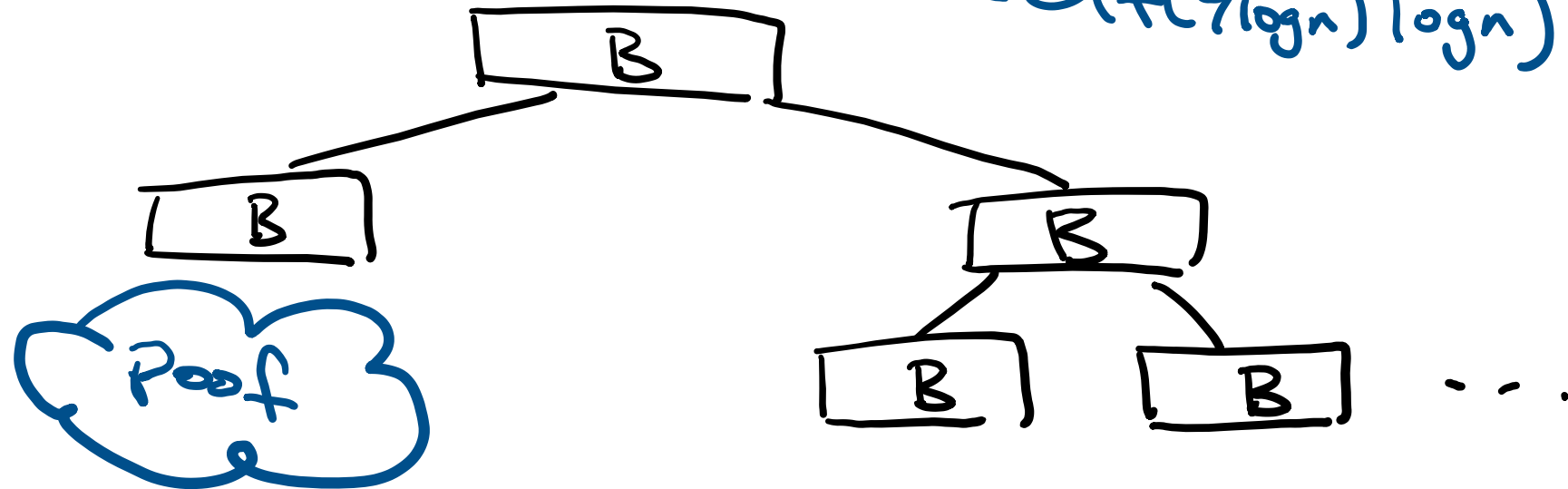
Suppose $f(\epsilon)$ space for ϵ -coreset.

$$\text{Set } B = f(\epsilon / \log n)$$

at each level:

$\epsilon / \log n$ -coreset
of child nodes

keep at most
 $2B$ points at
each level



Streaming Coresets

Reduce + Strong Merge Properties

$\Rightarrow$ use Merge & Reduce Paradigm

Suppose $f(\epsilon)$ space for ϵ -coreset.

Correctness?

by induction.

j -th level is $j \frac{\epsilon}{\log n}$ -coreset.

height = $O(\log n) \Rightarrow \epsilon$ -coreset at top.

$\Rightarrow O\left(\frac{(\log n)^2}{\epsilon}\right)$ space for streaming MEB

Space: $O(B \log^N B)$
 $= O(f(\epsilon/\log n) \log n)$

Clustering

k-center: Given $P \subseteq \mathbb{R}^d$, $k \in \mathbb{Z}$

find $C = \{c_1, \dots, c_k\}$ minimizing

$$\text{cost}(P, C) = \max_{p \in P} \min_{c \in C} \{d(p, c)\}.$$

MEB: k is always 1.

k-median

$$\text{cost}(P, C) = \sum_{p \in P} \min_{c \in C} d(p, c)$$

k-means

$$\text{cost}(P, C) = \sum_{p \in P} \min_{c \in C} d(p, c)^2$$

NP-hard
if k is
part
of input

Coreset for k -median

(k, ε) -coreset: $Q \subseteq P$ such that

for all $C \subseteq \mathbb{R}^d$, $|C| = k$,

$$(1 - \varepsilon) \text{cost}(P, C) \leq \text{cost}(Q, C) \leq (1 + \varepsilon) \text{cost}(P, C)$$

will need idea of weighted k -median

$$\text{cost}(P, C) = \sum_{p \in P} w(p) \min_{c \in C} d(p, c)$$

Coreset for k -median

(α, β) - bicriterion approx:

Find $A = \{a_1, \dots, a_m\}$ $m \leq \alpha k$

s.t. $\text{cost}(P, A) \leq \beta \text{opt}(P, k)$

Will convert into $(1+\epsilon)$ -approx
using k "centers"
via weighted ϵ -coreset.

(w/ prob $\geq 1-\delta$)

Coreset for k -median

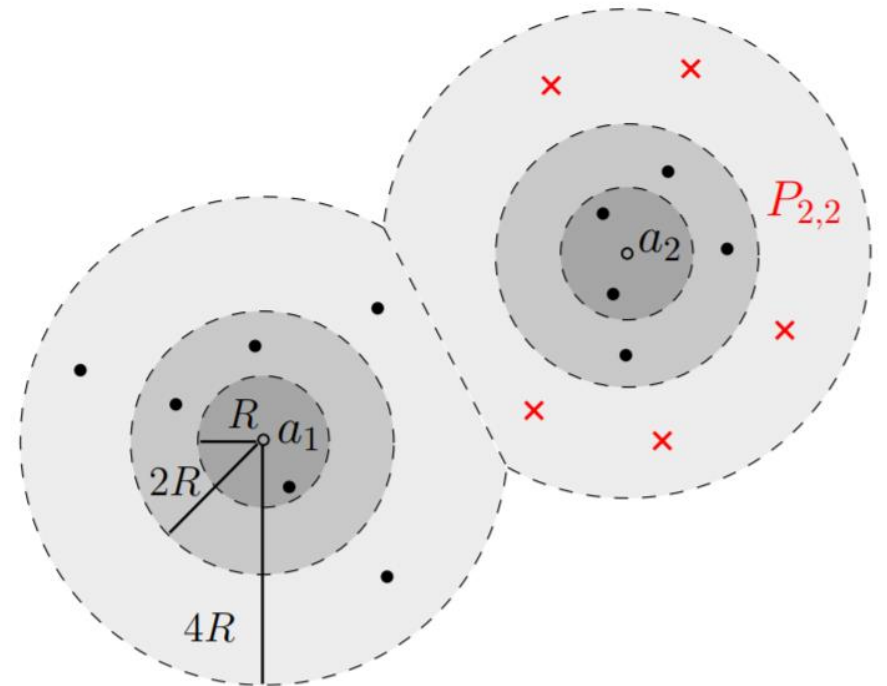
1. Let A be (α, β) approx to k -median

P_i : points in P "assigned" to a_i

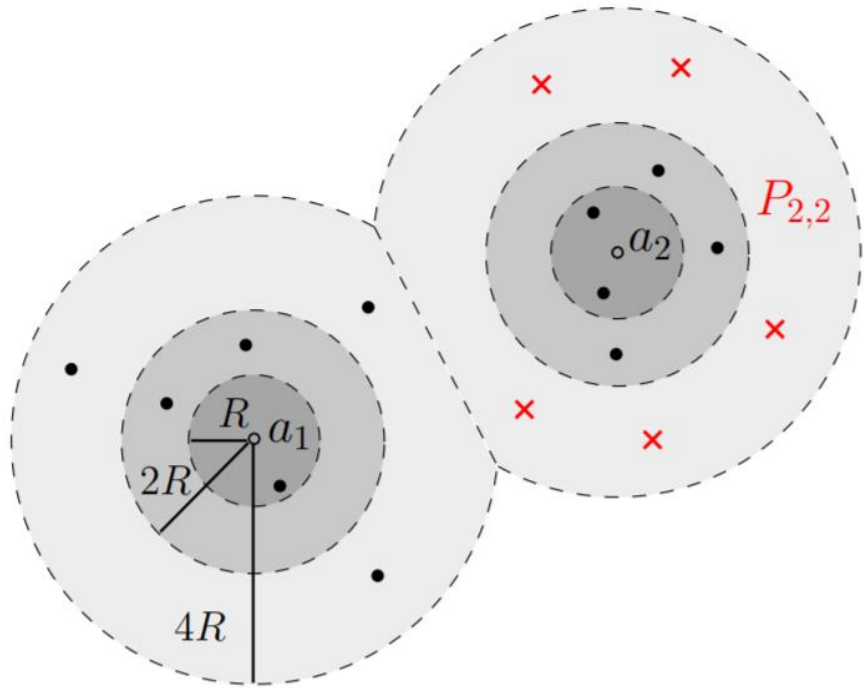
2. Split P_i into P_{ij} , $j \in \{0 \dots \lg(\beta n)\}$

P_{ij} = points in P_i w/ distance to a_i
between $2^{j-1}R$ & $2^j R$

$$R = \frac{\text{cost}(P, A)}{\beta n}$$



Coreset for k -median



3. Sample s points from P_{ij}

$$s = O\left(\frac{\beta^2}{\epsilon^2} (k \log n + \log \frac{1}{\delta})\right)$$

& assign weight $\frac{|P_{ij}|}{s}$

$$\rightarrow S_{ij} \subseteq P_{ij}.$$

Claim: $S = \bigcup_{i,j} S_{ij}$ is ϵ -coreset
w/ prob $\geq 1 - \delta$

Coreset for k -median

$$s = O\left(\frac{\beta^2}{\xi^2} (k \log n + \log \frac{1}{\delta})\right)$$

Key Lemma: $U = \text{sample } \frac{\ln(2/\Delta)}{\xi^2}$ points from V

Give each sample pt weight $\frac{|U|}{|V|}$

$$|\text{cost}(V, C) - \text{cost}(U, C)| \leq \xi |V| \text{diam}(V) \text{ w/ prob } \geq 1 - \Delta.$$

Sampling S_{ij} from $P_{ij} \Rightarrow$ need bound on
 $|P_{ij}| \text{diam}(P_{ij})$

"easy" calculation: $\sum |P_{ij}| \text{diam}(P_{ij}) \leq 6\beta \text{opt}(P, k)$

Coreset for k -median

$$s = O\left(\frac{\beta^2}{\varepsilon^2} (k \log n + \log \frac{1}{\delta})\right)$$

$$|\text{cost}(P_{ij}, c) - \text{cost}(S_{ij}, c)| \leq \xi |P_{ij}| \text{diam}(S_{ij}) \text{ w/ prob } \geq 1 - \Delta.$$

$$\sum |P_{ij}| \text{diam}(P_{ij}) \leq 6\beta \text{opt}(P, k)$$

$$\text{Set } \xi = \frac{\varepsilon}{6\beta}, \quad \Delta = \frac{n^{-2k} \delta}{2} \Rightarrow s = \frac{36\beta^2}{\varepsilon^2} \ln \frac{4n^{2k}}{\delta}$$

$$\begin{aligned} |\text{cost}(P, c) - \text{cost}(S, c)| &\leq \sum_{ij} |\text{cost}(P_{ij}, c) - \text{cost}(S_{ij}, c)| \\ &\leq \frac{\varepsilon}{6\beta} \sum_{ij} |P_{ij}| \text{diam}(P_{ij}) \leq \varepsilon \text{cost}(P, c) \end{aligned}$$

Coreset for k -median

$$s = O\left(\frac{B^2}{\varepsilon^2} (k \log n + \log \frac{1}{\delta})\right)$$

now solve k -median directly on ε -coreset
 $\Rightarrow (1+\varepsilon)$ -approximation.

Similar idea works for k -means.

!! Cost functions for k -median & k -means
satisfy strong merge $\Rightarrow$ streaming!!

